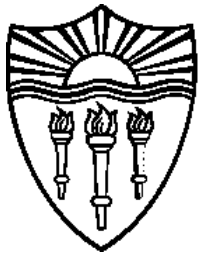

REPEATED ACTIVE SCREENING OF NETWORKS FOR DISEASES

Biswarup Bhattacharya, Han Ching Ou, Arunesh Sinha *,
Sze-Chuan Suen, Bistra Dilkina & Milind Tambe

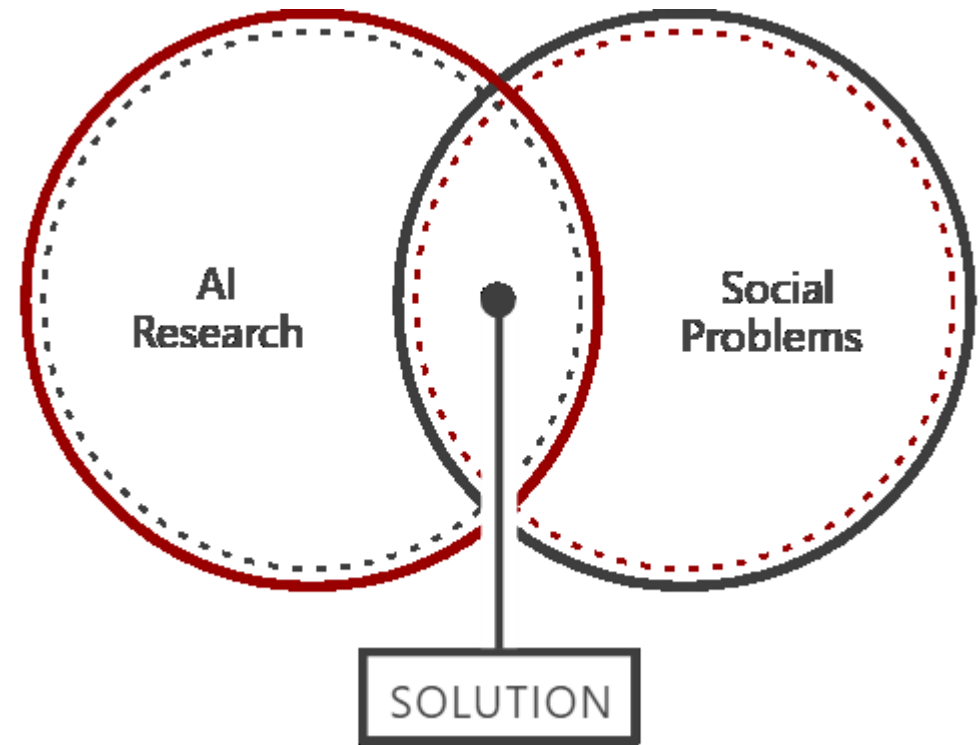
University of Southern California, * University of Michigan

epiDAMIK Workshop @ KDD 2018

AI FOR SOCIAL GOOD



USC University of
Southern California



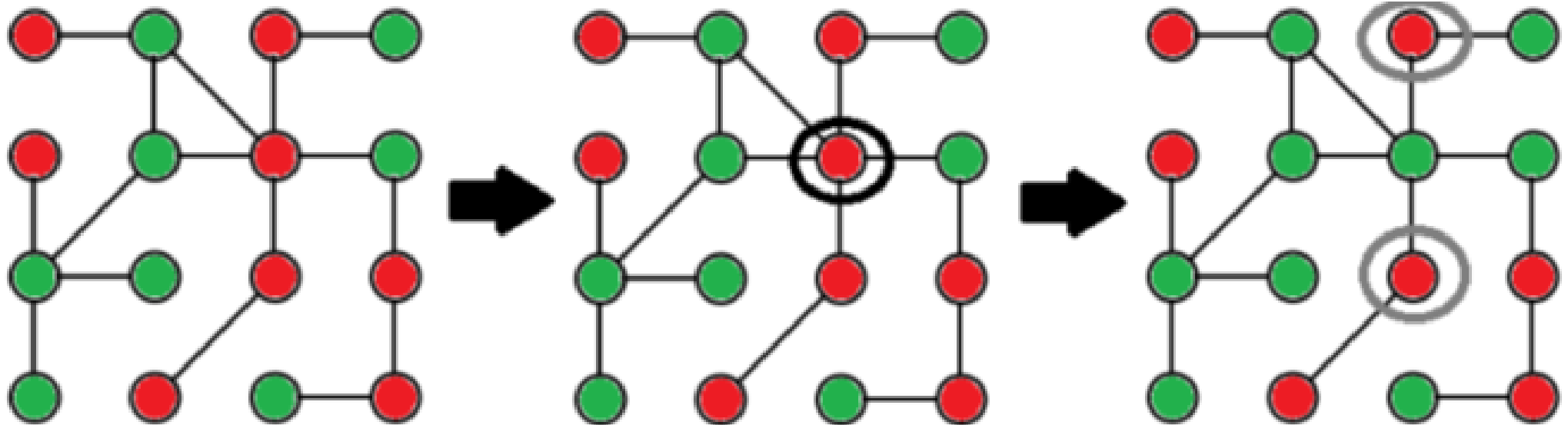
INTRODUCTION

- Number of health problems – AI can be utilized
- HIV, infectious diseases, nutrition, among others
- Curable infectious diseases
 - Tuberculosis - 10M+ people affected in 2016 [WHO]
- Minimizing the number of infected individuals

INTRODUCTION – ACTIVE SCREENING

- Individuals may not be able to seek treatment themselves
 - Distance from clinic, failure to self diagnose etc.
- Often – a matter of outreach and identification
 - Resource constraints – e.g. 1 health worker / 500 people (India)
- Problem of **Active Screening**
 - *Definition:* Individuals **sought out** by health workers and treated
- Passive Screening: Individuals seek treatment voluntarily

INTRODUCTION – ACTIVE SCREENING



- Which nodes to act on first?
- Which nodes to act on next?

PROBLEM STATEMENT

ACTS Problem

Given –

- A known network of individuals (n)
- Infectious disease parameters
- Limited resources (k)

Find – An active screening policy

To maximize – Number of healthy individuals over time

STATUS QUO

Previous works generally do not consider:

- Multiple timesteps
- Uncertainty in health states
- Latent stages
- Lack of permanent immunity

As discussed: Hard to predict infected nodes

In the field: Heuristics used – degree, high-risk societies

CONTRIBUTIONS

1. ACTS Active Screening Model

- POMDP-like model

2. TRACE Algorithm for ACTS

- **Synergy of 3 Key Ideas:** Greedy, eigenvalue & community
- Practically significant results of increase in healthy population

OVERVIEW

1. Problem Modeling

- SEIS Disease Model
- Active Screening Model

2. TRACE Algorithm

- Belief States & Attractiveness Score (FIRST KEY IDEA)
- Dynamic Eigenvalue (SECOND KEY IDEA)
- Community Formation (THIRD KEY IDEA)

3. Experiments

OVERVIEW

1. Problem Modeling
 - SEIS Disease Model
 - Active Screening Model
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SEIS COMPARTMENTAL DISEASE MODEL

Susceptible (S) $\xrightarrow{\alpha}$ Exposed (E)

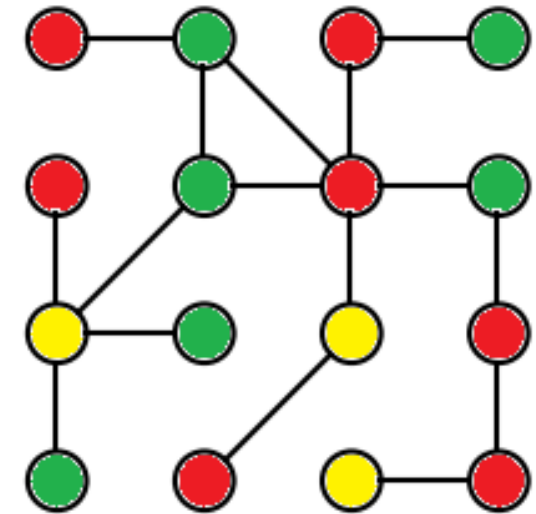
Exposed (E) $\xrightarrow{\beta}$ Infected (I)

Infected (I) \xrightarrow{c} Susceptible (S)

- 3 states – S (healthy), E (exposed, cannot infect others), I (infected)
- Note: c is the probability individuals voluntarily screen themselves
- Latent stage (E) + Lack of permanent immunity

ACTIVE SCREENING MODEL – [S], [A], T, O, Z, R

- n individuals $\Leftrightarrow n$ nodes
- Each node's state – S, E or I
- States not readily known by us (agents)
- Action: Screen (1) or not screen (0)
 - $k (< n)$ individuals to be screened at each stage



ACTIVE SCREENING MODEL – S, A, [T], O, Z, R

- Cyclic and unidirectional: $S \rightarrow E \rightarrow I$

Susceptible (S) $\xrightarrow{\alpha}$ Exposed (E)

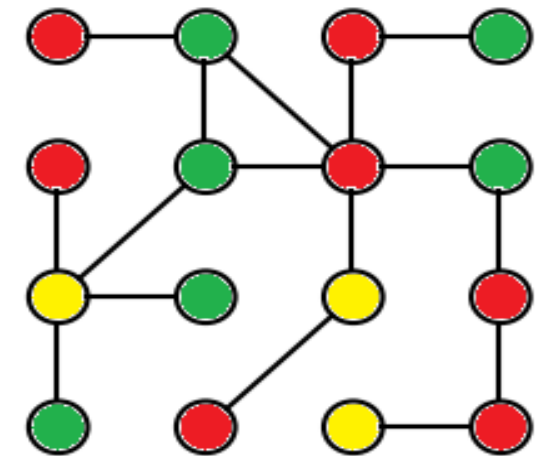
Exposed (E) $\xrightarrow{\beta}$ Infected (I)

Infected (I) \xrightarrow{c} Susceptible (S)

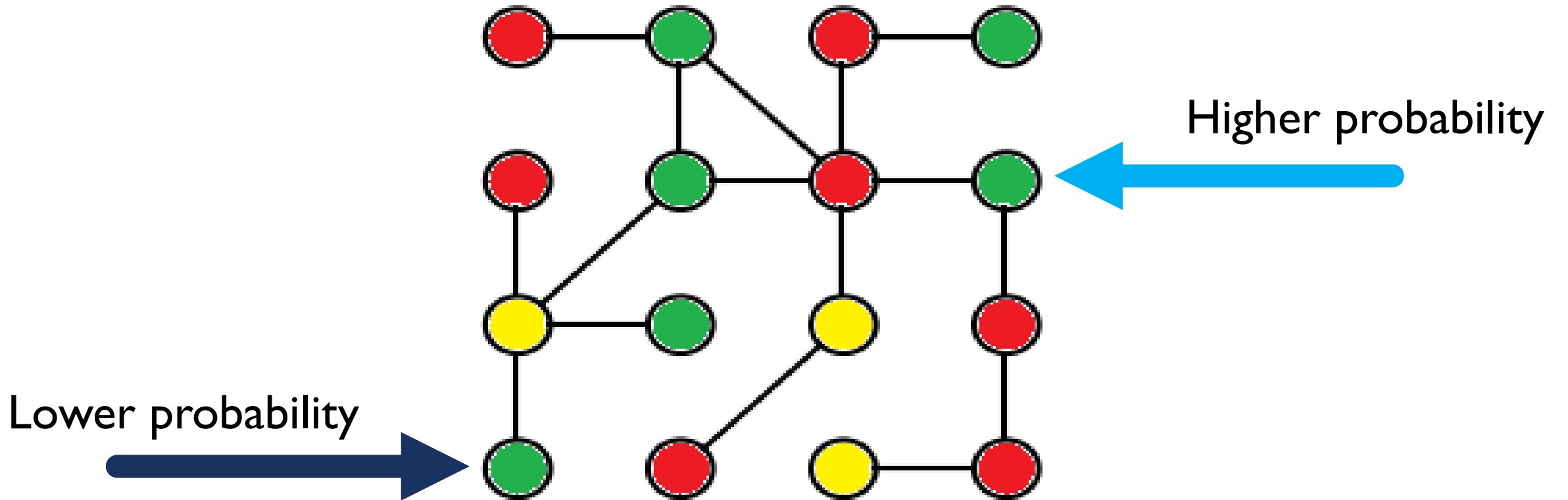
- From Row state To Column state

- $q(j)$: Number of infected neighbors of node j

$$T^0 = \begin{matrix} & S & E & I \\ \begin{matrix} S \\ E \\ I \end{matrix} & \begin{bmatrix} q_j & 1 - q_j & 0 \\ 0 & 1 - \beta & \beta \\ c & 0 & 1 - c \end{bmatrix} \end{matrix}, \quad T^1 = \begin{matrix} & S & E & I \\ \begin{matrix} S \\ E \\ I \end{matrix} & \begin{bmatrix} q_j & 1 - q_j & 0 \\ 1 & 0 & 0 \\ 1 & 0 & 0 \end{bmatrix} \end{matrix}$$

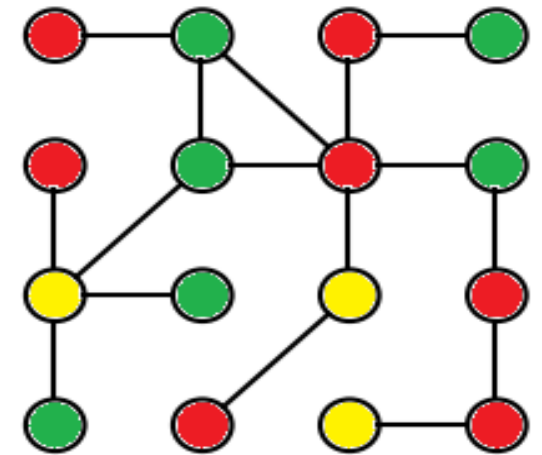


ACTIVE SCREENING MODEL – S, A, [T], O, Z, R



ACTIVE SCREENING MODEL – S, A, T, [O], [Z], R

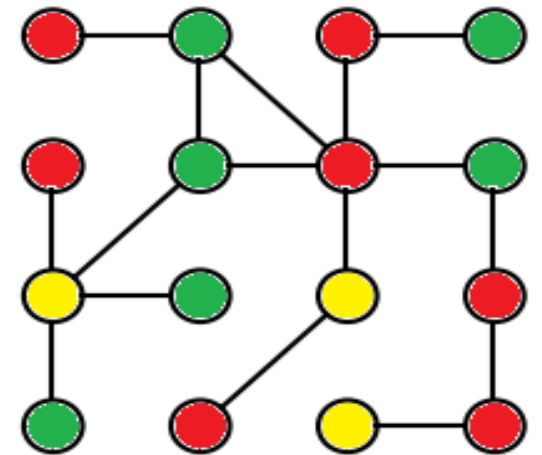
- Actual health state observed on screening ($a=1$)
- Else, no observation



ACTIVE SCREENING MODEL – S, A, T, O, Z, [R]

- +1 for every healthy (S) individual
- In shown network, R = +6
- Objective: Maximize increase in number of disease-free half-years over no intervention

$$\sum_{t=0}^{t=T} |S|_t$$



WHY NOT POMDP? – SCALABILITY

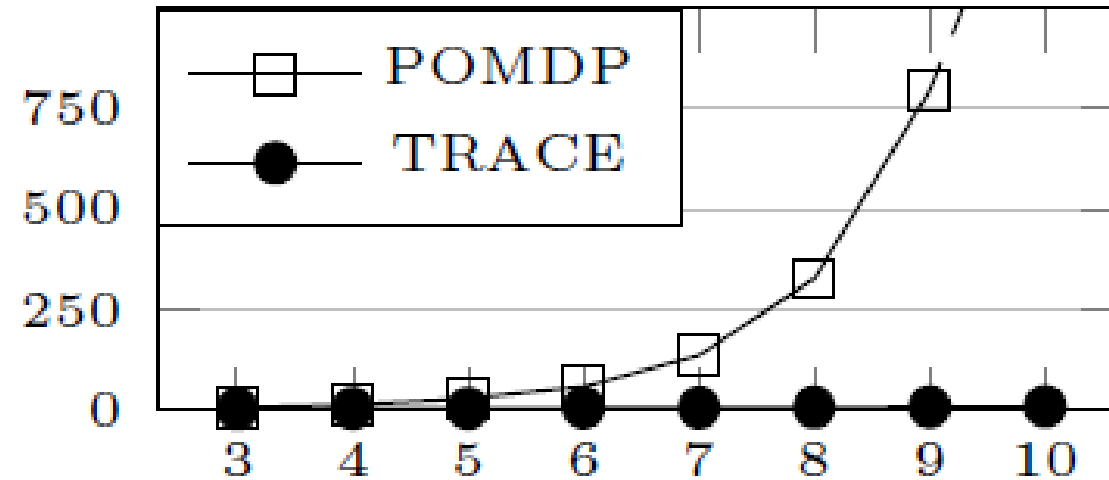


Figure: Runtime (s) v/s n

OVERVIEW

1. Problem Modeling

2. TRACE Algorithm

- Belief States & Attractiveness Score (FIRST KEY IDEA)
- Dynamic Eigenvalue (SECOND KEY IDEA)
- Community Formation (THIRD KEY IDEA)

3. Experiments

TRACE ALGORITHM

- Generates an online POMDP policy
- Synergy of three approaches:
 1. Community [Hendrickson and Leland, 1995]
 2. Beliefs (Greedy)
 3. Eigenvalues [Prakash et al., 2012]

HOW TO HANDLE UNKNOWN STATES?

- Maintain beliefs

$$b_i^t = [b_{i,S}^t, b_{i,E}^t, b_{i,I}^t]$$

- Maintaining marginals good enough [Chakrabarti et al., 2008]
- Other representations – prohibitively large
- Belief update rules – similar to T matrices

HOW TO HANDLE UNKNOWN STATES?

- Maintain **beliefs** for EVERY node $\rightarrow O(3 \times n)$ space

$$b_i^t = [b_{i,S}^t, b_{i,E}^t, b_{i,I}^t]$$

- Maintaining marginals good enough [Chakrabarti et al., 2008]
- Other representations – prohibitively large

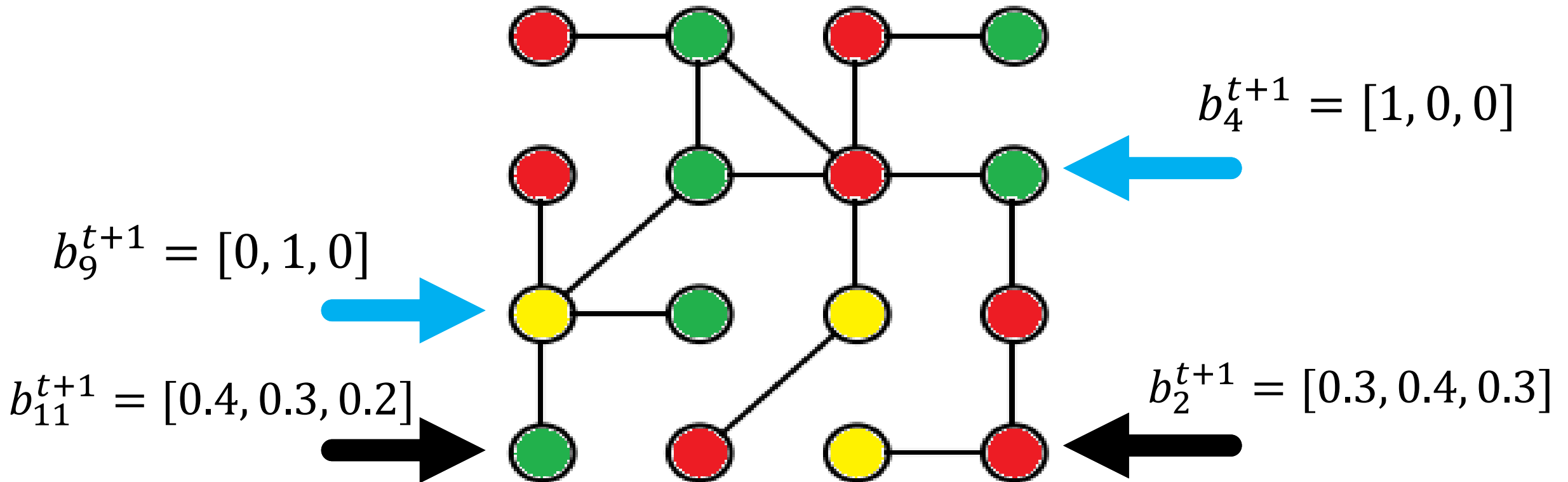
BELIEF STATES UPDATE

$$b_i^t = [b_{i,S}^t, b_{i,E}^t, b_{i,I}^t]$$

- Belief update rules ($b_i^t \rightarrow b_i^{t+1}$) – similar to T matrices
- Start with [0.33, 0.33, 0.33] belief for all
- Belief set to actual state for nodes screened in current timestep
 - E.g. Change to [1,0,0] on screening S node, [0,1,0] if E, [0,0,1] if I
- Update normally if not screened in current timestep

BELIEF STATES – EXAMPLE UPDATE (T=0 → T=1)

If nodes with **light arrows** are screened (initially all beliefs are $[0.33, 0.33, 0.33]$)



FIRST KEY IDEA

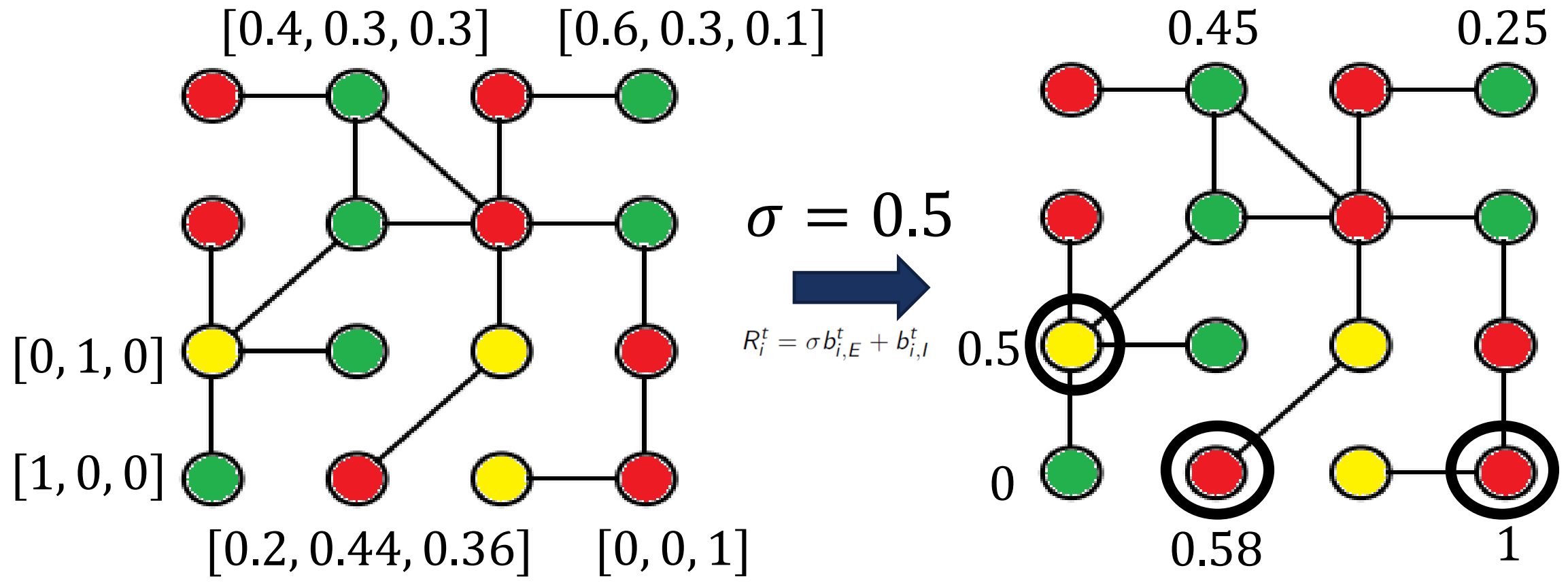
GREEDY

- Attractiveness score for every node based on **beliefs**

$$R_i^t = \sigma b_{i,E}^t + b_{i,I}^t$$

- Simply screen based on higher score
- Possibly not optimal

GREEDY SELECTION



TOWARDS OPTIMALITY

EIGENVALUES

- An epidemic dies out iff

$$\frac{\alpha}{c} < \frac{1}{\lambda_A^*} \text{ and } \beta \neq 0. \quad [\text{Prakash et al., 2012}]$$

- λ_A^* = largest eigenvalue of the adjacency matrix A of a graph
- High α and/or low c make the limit harder to achieve

SECOND KEY IDEA – DYNAMIC EIGEN

$$\frac{\alpha}{c} < \frac{1}{\lambda_A^*} \text{ and } \beta \neq 0 .$$

- “Remove” nodes such that λ_A^* decreases \rightarrow increases $1/\lambda_A^*$
- S nodes cannot infect neighbors \rightarrow remove S nodes
- Our case: multiply each row by $(1 - b_{i,S}^t)$
- Iteratively remove + check \rightarrow slow for large n

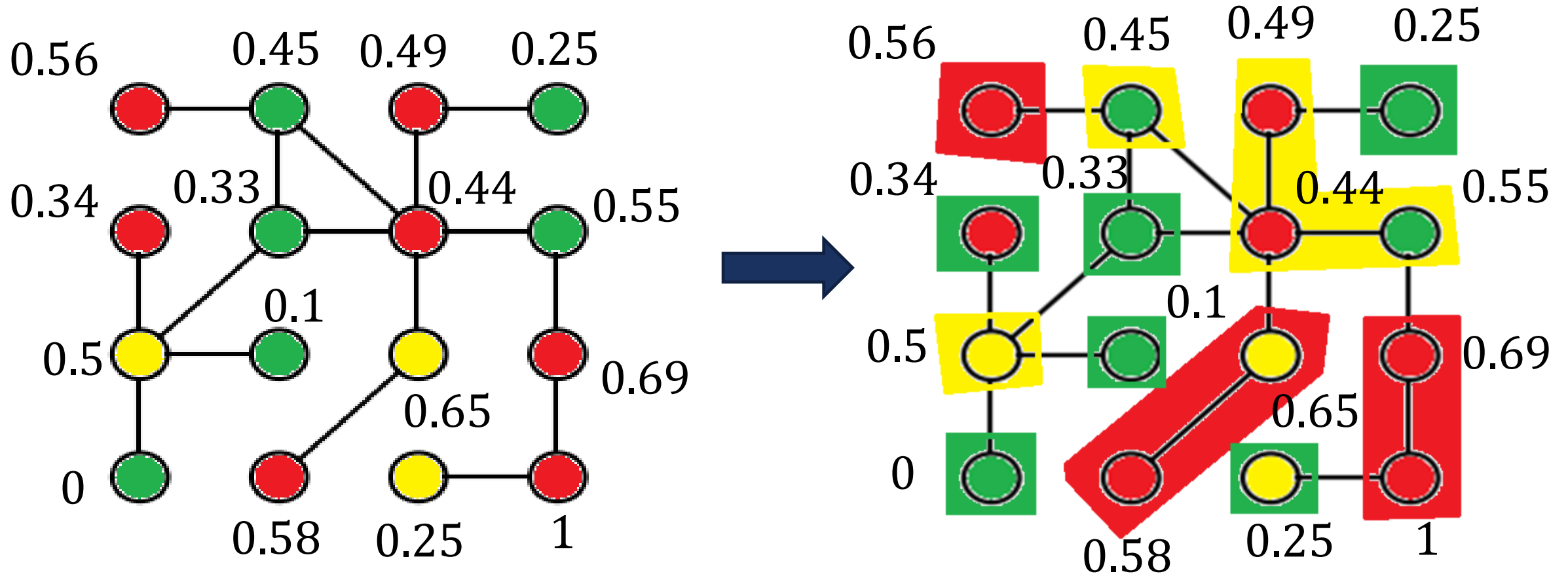
THIRD KEY IDEA – SPEEDING UP DYNAMIC EIGEN

COMMUNITIES

- Group nodes by attractiveness scores
- *Coarsening* [Hendrickson & Leland, 1995]
- Number of groups $\leq n \rightarrow$ DynamicEigen scales up
- Can be proven for scale-free graphs:

$$\text{number of groups} = O\left(\frac{1.5}{d} n\right) \quad (d = \text{average degree})$$

COMMUNITIES – GRAPH COARSENING



TRACE ALGORITHM – THREE STEPS

1. Greedy approach: Belief information [Unknown health states]
2. Community-based approach: Grouping nodes [Speeds up next step]
3. Eigenvalue-based approach: Reducing spectral radius [Optimality]

None superior by itself! (7 observations in extended version)

OVERVIEW

1. Problem Modeling
2. TRACE Algorithm
3. Experiments

NETWORKS

- 10 real-world networks in extended version ($n = 75$ to 16730)
- 3 in epiDAMIK submission ($n = 202$ to 1899)
 1. India ($n = 202$, [Banerjee et al., 2013]): Collected from a rural Indian village
 2. Infectious Exhibition ($n = 410$, [Isella et al., 2011])
 3. Irvine ($n = 1899$, [Opsahl & Panzarasa, 2009])

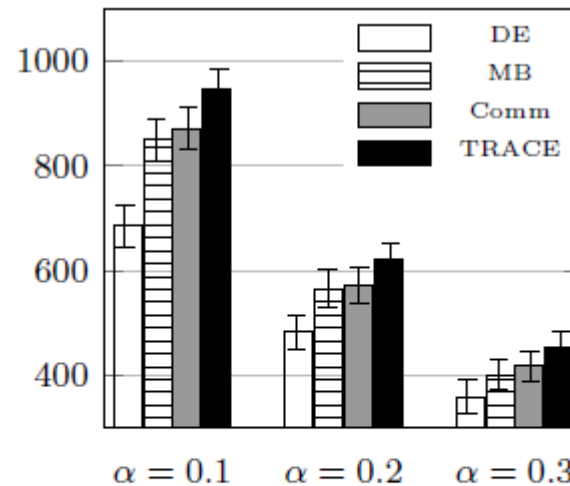
SETUP

- $\alpha = 0.1 - 0.3, \beta = 0.25, c = 0.2 - 0.6$
- Each round = 6 months
- Total simulation = 10 years
- $k = 5\%, \sigma = 0.5$
- Metric: Increase in number of disease-free half-years over no intervention

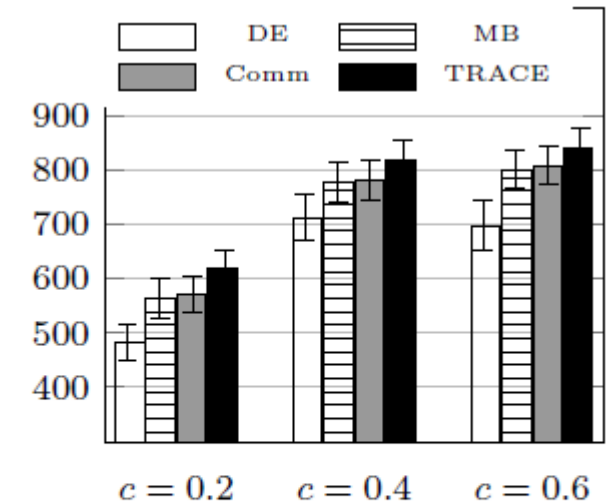
$$\sum_t |S|_{t,algo} - \sum_t |S|_{t,none}$$

RESULTS – VARYING PARAMETERS

- MB: Greedy
- DE: Just DynamicEigen without community
- Comm: 0-1 knapsack select without eigen



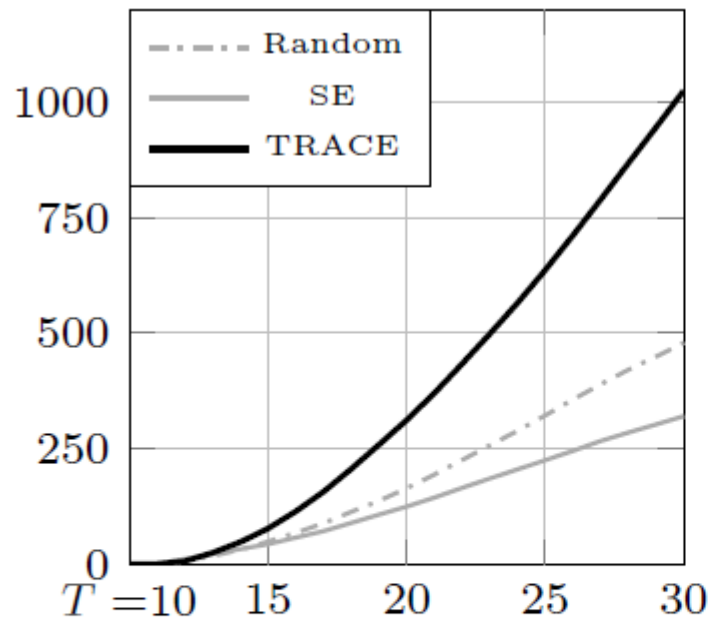
(c) Varying α ($c = 0.2$)



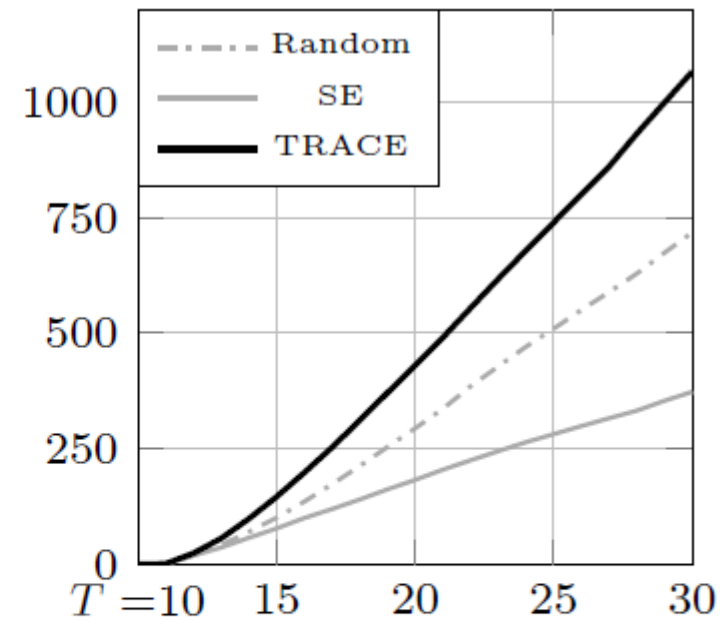
(d) Varying c ($\alpha = 0.2$)

Figure: Performance by TRACE components (India network)

RESULTS – OVER TIME



(a) India network



(b) Exhibition network

Increase in $\sum_{t=0}^{t=T} |S|_t$ over None for varying T
($\alpha = 0.1, \beta = 0.25, c = 0.2$)

KEY TAKEAWAYS

- ✓ **Hard problem** – Multi-round + SEIS + unknown health states
- ✓ **Belief states** to estimate the uncertain health status
- ✓ \downarrow **spectral radius** \Rightarrow \downarrow disease prevalence
- ✓ **Three approaches**: Eigenvalue, community, greedy
- ✓ TRACE \rightarrow **practically significant** results

FUTURE WORK

- Addressing TB in India



- Future: Complex disease models, birth and death, costs, network uncertainty



THANK YOU!

“TRACE: Algorithmic ACTS for Preventing the Spread of
Recurrent Infectious Diseases on Networks”

bbhattac@usc.edu

<https://biswarupb.github.io/>